

**AMENDMENTS TO THE CLAIMS:**

This listing of claims will replace all prior versions, and listings, of claims in the application:

**LISTING OF CLAIMS:**

1. (Currently Amended) A composite planetary device, comprising:  
a planetary gear mechanism equipped with a sun gear, at least one planetary gear and an internal gear; and  
a planetary roller mechanism equipped with a sun roller, at least one planetary roller and a ring roller~~[[,]]~~;  
wherein the sun gear and the sun roller are integrally rotated around a common rotating center axis, the corresponding planetary gear and the planetary roller are integrally rotated around a common planetary shaft, and the internal gear and the ring roller rotate integrally around the rotating center axis or can be fixed concentrically,  
wherein a radius of the sun roller is larger by ~~[[ $\Delta r_1$ ]]~~  $(\Delta r_1)$  than a radius ~~[[ $r_1$ ]]~~  $(r_1)$  of a working pitch circle of the sun gear,  
a radius of the planetary roller is smaller by ~~[[ $\Delta r_1$ ]]~~  $(\Delta r_1)$  than a radius ~~[[ $r_{21}$ ]]~~  $(r_{21})$  of a working pitch circle of the planetary gear,  
the radius ~~[[ $r_{21}$ ]]~~  $(r_{21})$  of the working pitch circle of the planetary gear meshing with the sun gear is larger than a radius ~~[[ $r_{23}$ ]]~~  $(r_{23})$  of a working pitch circle of the planetary gear meshing with the internal gear.

2. (Currently Amended) The composite planetary device according to claim 1, wherein

gears of the planetary gear mechanism have numbers of teeth that satisfy equation (1), the radius of the sun roller is larger than the radius of the working pitch circle of the sun gear by a radius increase amount  $[\Delta r_1]$  ( $\Delta r_1$ ) given by equation (2),

the radius of the planetary roller is larger than the radius of the working pitch circle of the planetary gear meshing with the internal gear by an amount  $[\Delta r_2]$  ( $\Delta r_2$ ) given by equation (3)  $[\Delta r_2]$

$$j = (Z_d - Z_a)/2 - Z_b > 0 \quad (1)$$

where Here  $j$ : Planetary gear teeth reduction number

$Z_a$ : Number of sun gear teeth

$Z_b$ : Number of planetary gear teeth

$Z_d$ : Number of internal gear teeth

$$\Delta r_1 = \frac{r_{21} - r_{23}}{\frac{r_{23}(1 + \frac{r_1}{r_{21}})}{\frac{r_{21}}{r_1(1 - \frac{r_{23}}{r_3})} + 1}} \quad (2)$$

where Here  $r_1$ : Radius of working pitch circle of sun gear

$r_{21}$ : Radius of the working pitch circle of the planetary gear meshing with the sun gear

$r_{23}$ : Radius of the working pitch circle of the planetary gear meshing with the internal gear

$r_3$ : Radius of the working pitch circle of the internal gear

$$\Delta r_2 = r_{21} - r_{23} - \Delta r_1 \quad (3)$$